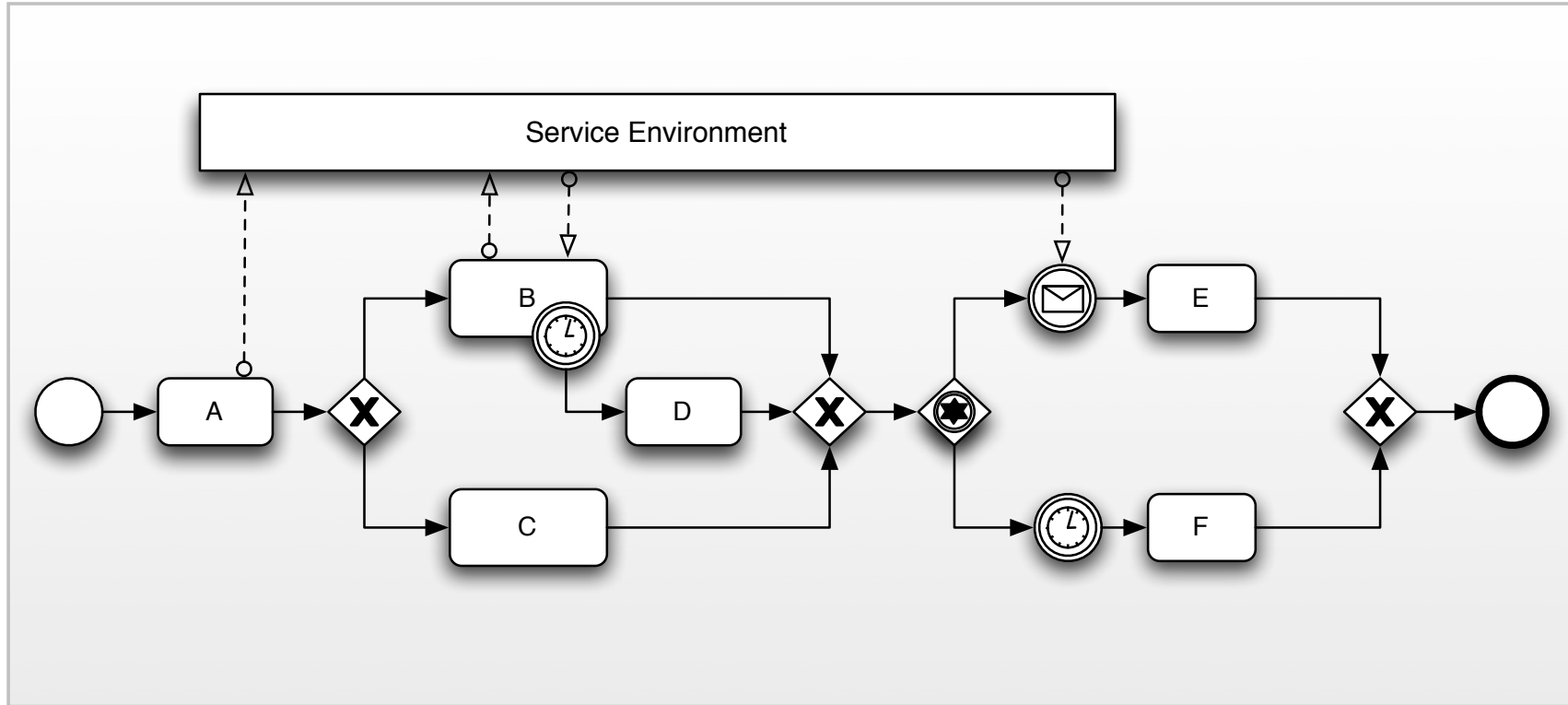


Towards a Formal Model for Agile Service Discovery and Integration

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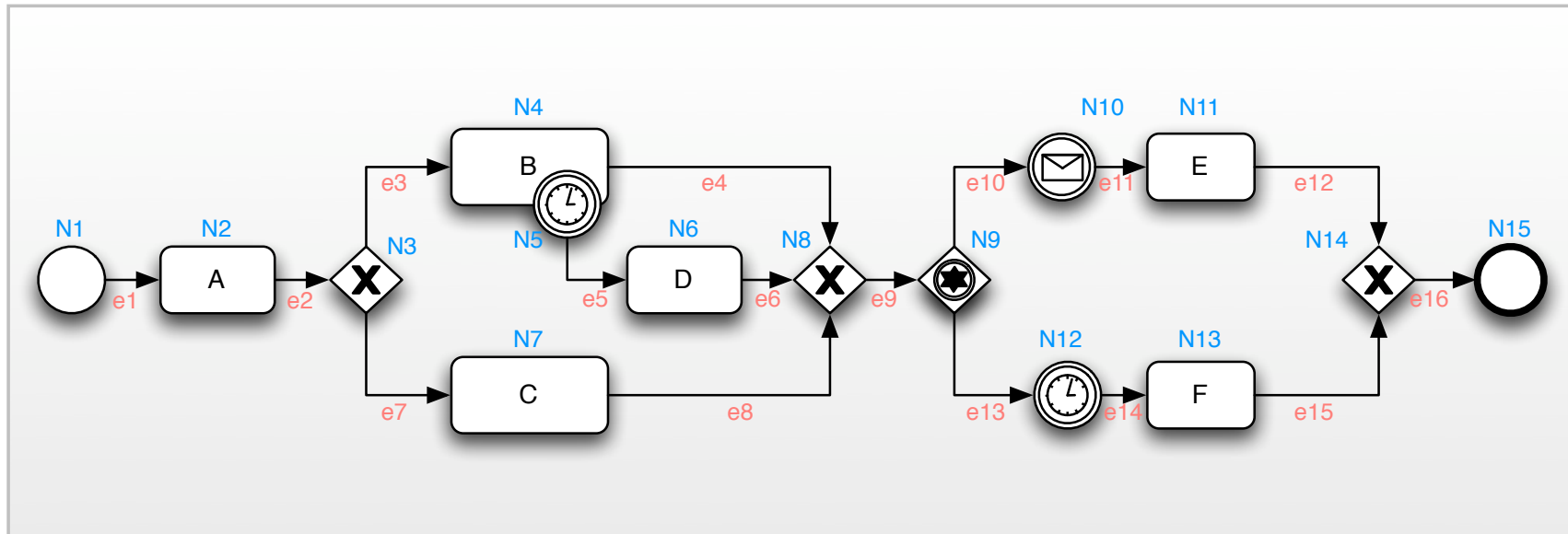
Goals

- To enable agile service discovery and invocation
- Formal Representation of
 - orchestrations as well as
 - choreographies
- Using a process algebra that provides dynamic process structures \Rightarrow Pi-Calculus
- Extend work on representing workflow pattern formalizations to the SOC domain



Example in BPMN

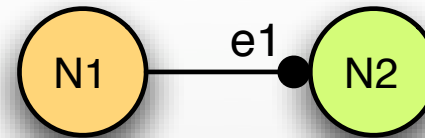
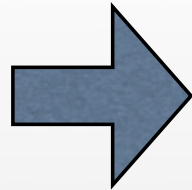
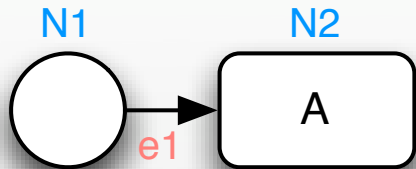
Orchestration



Mapping to the Pi-Calculus

Mapping strategy

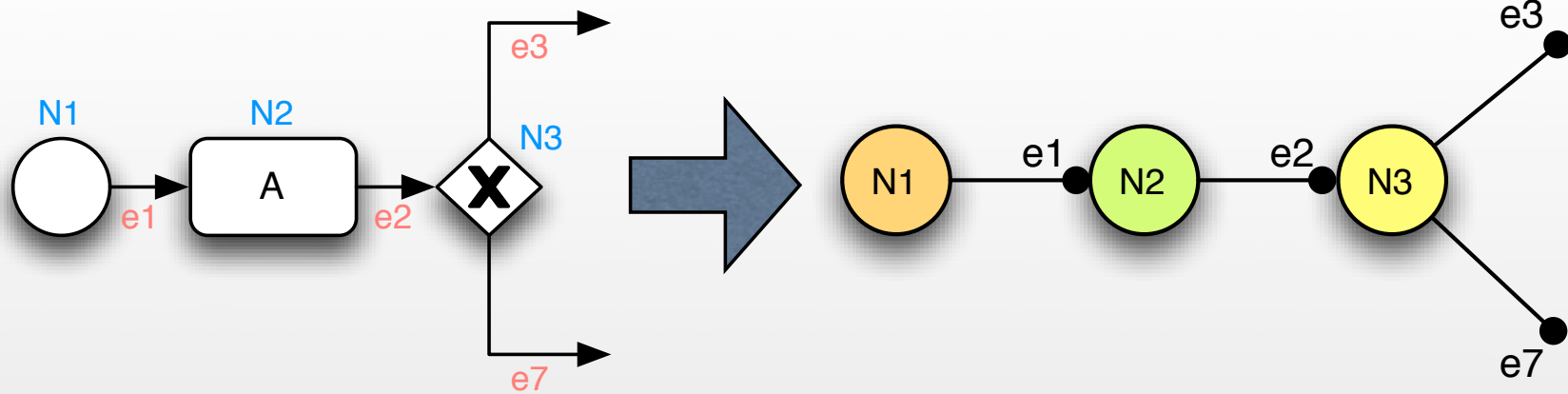
- Match all (workflow) patterns to their corresponding Pi-Calculus representation
- Paper: Using the Pi-Calculus for Formalizing Workflow Patterns (Puhlmann, Weske)



$$N1 = evn_{START}.\bar{e1}.0$$

$$N2 = e1.\tau_{N2}.\bar{e2}.0$$

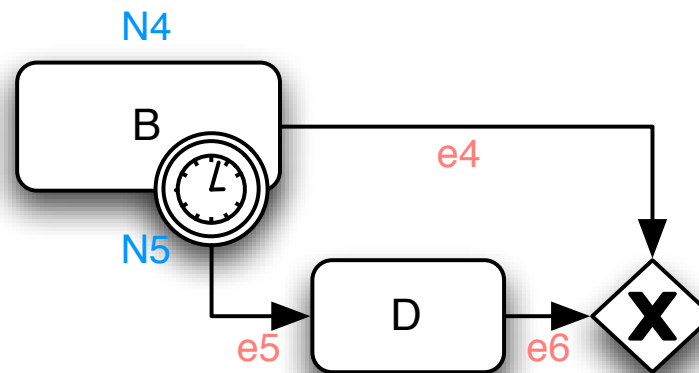
Sequence



Exclusive Choice

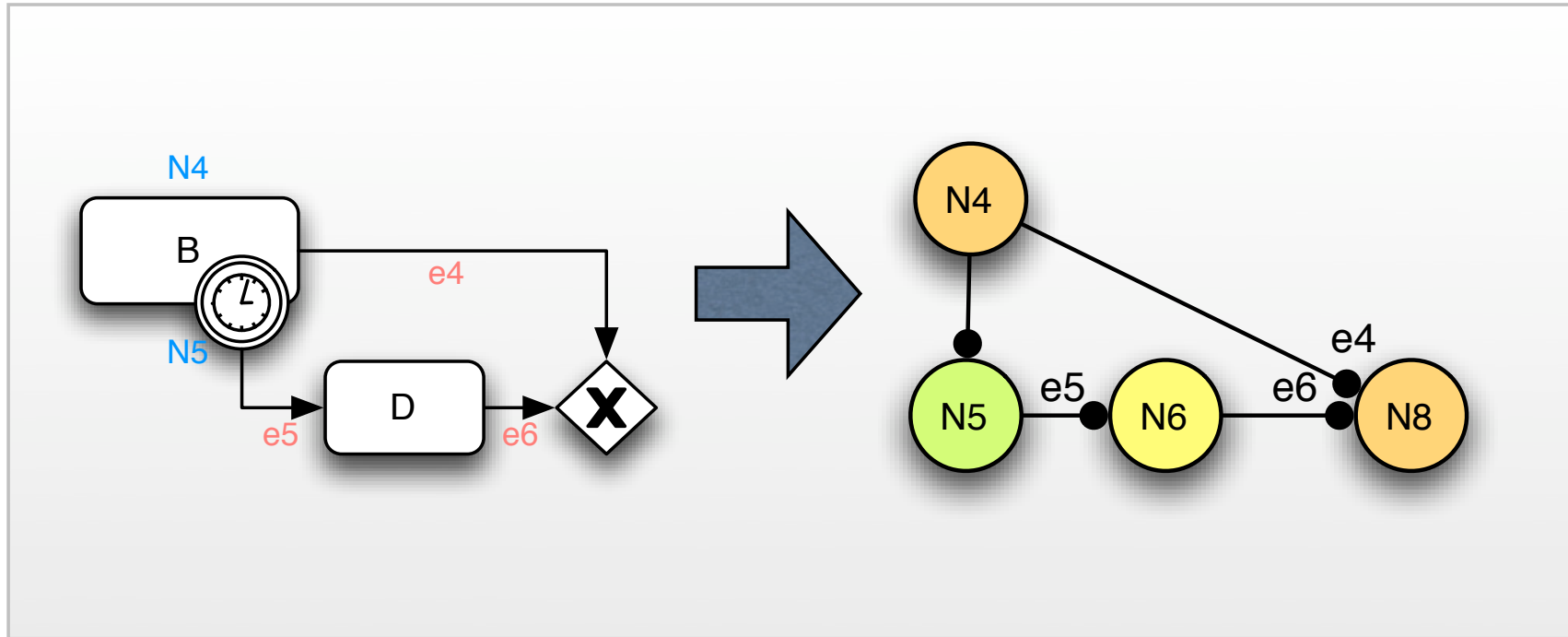
Hold on!

- What about this construct?



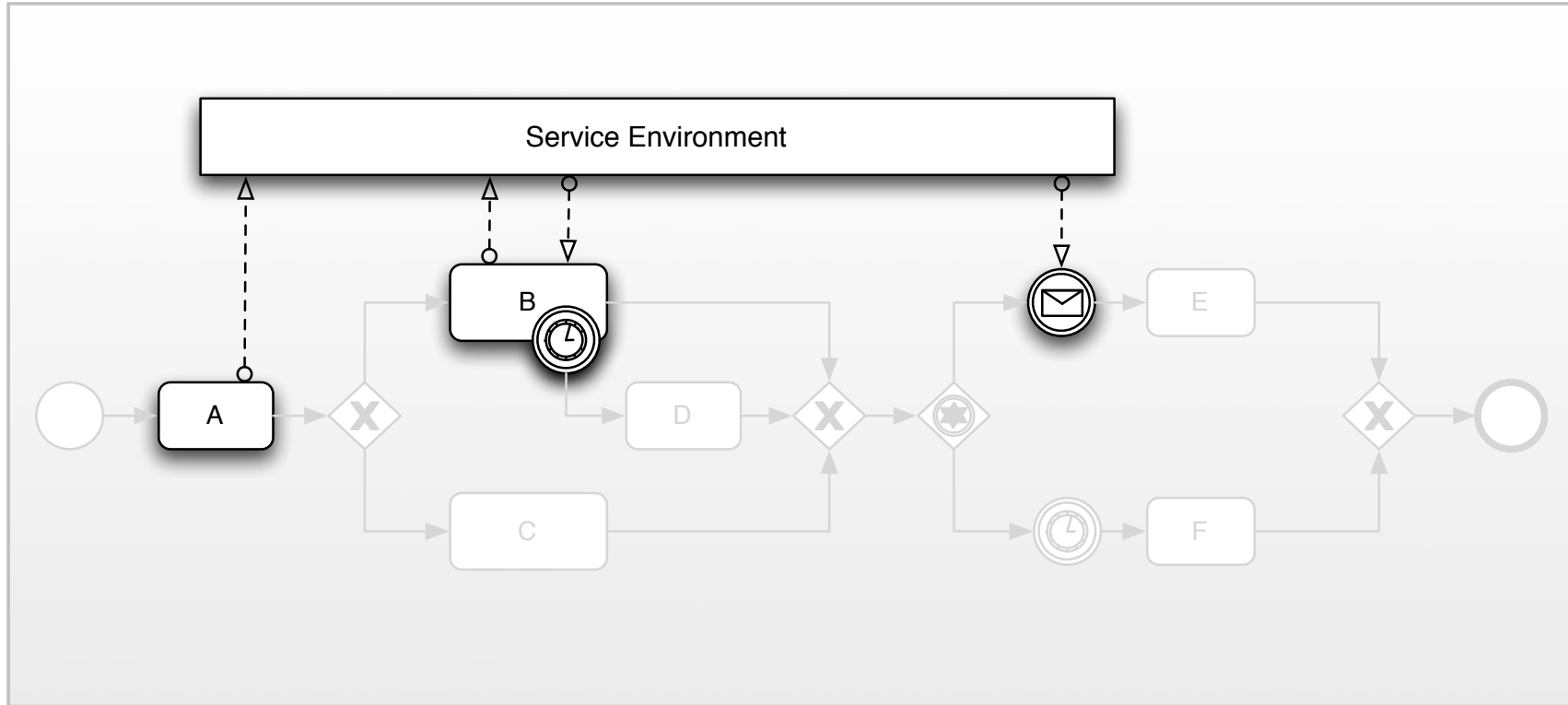
Event-based Rerouting

- New pattern!
- Represents the change of the control flow based on an event (e.g. a message) that occurs during the execution of an activity
- However, we can not stop the actual activity, only reroute the control flow immediately



Event-based Rerouting

Choreography



Choreography

Correlations

- Pi-calculus supports the concepts of dynamic channel creation via the new operator (\mathbf{v})
 - Each channel provides:
 - a unique identification and
 - a communication channel
- ➔ Sufficient for correlations!

Service Invocation

- Algorithm:
 - Create a new channel (a Pi-Calculus name)
 - Invoke the server with the channel and request as a parameter
 - Wait for a response on the link
- Advantage: The link can be used as an identifier as well as an unique response channel, so no additional formalism or handling is required

$$\forall ch \overline{service}\langle ch, request \rangle.ch(response)$$

Formal Service Invocation

Asynchronous/ Synchronous Invocation

- The introduced concept is always asynchronous:
- Request/Response can be split over different Pi-Calculus processes
- If there are no operations between the request and response, we can call it “synchronous invocation”

$$\begin{aligned}
N1 &= \text{TASK}(env_{START}, e1, env_{ABORT}, \tau_{N1}) \\
N2 &= \text{TASK}(e1, e2, env_{ABORT}, \overline{w_{req1}} \langle w_{resp1} \rangle . \tau_{N2}) \\
N3 &= e2 . \tau_{N3} . ([c_{e3} = \top] \overline{e3} | [c_{e7} = \top] \overline{e7}) \\
N4 &= \text{TASK}(e3, e4, abort_{N5}, \overline{w_{req2}} \langle w_{resp2} \rangle . w_{resp2} . \tau_{N4}) . \mathbf{0} \\
N5 &= env_{TIMEOUT_{N5}} . \overline{abort_{N5}} \langle e5 \rangle \\
N6 &= \text{TASK}(e5, e6, env_{ABORT}, \tau_{N6}) \\
N7 &= \text{TASK}(e7, e8, env_{ABORT}, \tau_{N7}) \\
N8 &= \mathbf{vx}(e4 . \overline{x} . \mathbf{0} | e6 . \overline{x} . \mathbf{0} | e8 . \overline{x} . \mathbf{0} | x . \overline{e9} . \mathbf{0}) \\
CHOICE_{N9, N10, N12} &= e9 . (w_{resp2} . \overline{e11} . \mathbf{0} + env_{TIMEOUT_{N12}} . \overline{e14} . \mathbf{0}) \\
N11 &= \text{TASK}(e13, e14, env_{ABORT}, \tau_{N11}) \\
N13 &= \text{TASK}(e14, e15, env_{ABORT}, \tau_{N13}) \\
N14 &= \mathbf{vx}(e12 . \overline{x} . \mathbf{0} | e15 . \overline{x} . \mathbf{0} | x . \overline{e16} . \mathbf{0}) \\
N15 &= \text{TASK}(e16, env_{DONE}, env_{ABORT}, \tau_{N15})
\end{aligned}$$

Formal Representation

Conclusion & Further Work

- We (partly and illustrating) showed how to use the Pi-Calculus in the service-oriented domain
- The Pi-Calculus has its pro's in supporting
 - Choreographies (esp. correlations)
 - while also allowing powerful service orchestrations incl. extensions to new patterns
- However, more research is required, e.g.
 - formal reasoning (service equivalence, soundness)
 - or precise mappings from graphical notations

Want more?

- <http://pi-workflow.org>