## Business Process Management

Workflow and Data Patterns:A formal semantics

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## Foundations

- The Formalization of Workflow Patterns is based on ECA rules


## ECA Rules

- ECA rules from active databases:
- (on) Event,
- (if) Condition,
- (then) Action
- Different Coupling Modes
- Different Triggers


# ON inserting a row in course registration table IF over course capacity <br> THEN abort registration transaction 

## Example: ECA rule

ON inserting a row in course registration table
IF over course capacity
THEN notify registrar about unmet demands

ON inserting a row in course registration table
IF over course capacity
THEN put on waiting list

## Example: ECA Conflicts

CREATE TRIGGER LimitSalaryRaise AFTER UPDATE OF Salary ON Employee REFERENCING OLD AS 0, NEW AS N FOR EACH ROW
WHEN (N.Salary - O.Salary > 0.05*O.Salary)
UPDATE Employee
SET Salary $=1.05 *$ O.Salary
Where Id = O.ld
Business Rule Enforced with AFTER trigger

## Event-based Routing

- The ECA approach has been adapted to workflows:
- I Event
- m Conditions
- n Actions



## ECA Notation



## ECA Sequence Flow



## ECA Parallel Flow



## ECA Choice

## Mapping Workflow Activities to Agents

- Each workflow activity is mapped to a concurrent pi-calculus agent:
- Each agent has pre- and post-conditions
- Pre-condition $=$ Event and Condition
- Postcondition $=$ Action

$$
x \cdot[a=b] \tau \cdot \bar{y} . \mathbf{0}
$$

## Basic Activities in the $\mathrm{Pi}-\mathrm{Calculus}$

## Basic Control Flow Patterns

- The basic control flow patterns capture elementary aspects of control flow



## Sequence



## Parallel Split



## Synchronization



## Exclusive Choice



## Simple Merge

# Advanced Branching and Synchronization Patterns 

- The advanced branching and synchronization patterns require advanced concepts and map only partly to the basic activity template



## Multiple Choice

$$
\begin{aligned}
& B=\tau_{B} \cdot \overline{d_{1}} \cdot \mathbf{0} \\
& C=\tau_{C} \cdot \overline{d_{2}} \cdot \mathbf{0} \\
& D=d_{1} \cdot \tau_{D} \cdot D^{\prime}+d_{2} \cdot \tau_{D} \cdot D^{\prime}+d_{1} \cdot d_{2} \cdot \tau_{D} \cdot D^{\prime}
\end{aligned}
$$

## Synchronizing Merge



## Multiple Merge



## Discriminator

$$
D=(\mathbf{v} h, \text { exec })\left(\left(\prod_{i=1}^{m} d_{i} \cdot \bar{h} . \mathbf{0}\right)\left|h . \overline{e x e c} .\{h\}_{1}^{m-1} \cdot D\right| \text { exec. } \tau_{D} \cdot D^{\prime}\right)
$$

## Discriminator Template

$$
D=(\mathbf{v} h, \text { exec })\left(\left(\prod_{i=1}^{m} d_{i} \cdot \bar{h} \cdot \mathbf{0}\right)\left|\{h\}_{1}^{n} \cdot \overline{\text { exec }} .\{h\}_{n+1}^{m} \cdot D\right| \text { exec. } \tau_{D} \cdot D^{\prime}\right)
$$

## N-out-of-M-Join Template

## Structural Patterns

- Structural patterns show restrictions on workflow languages


$$
\begin{aligned}
& A=!a \cdot \tau_{A} \cdot \bar{b} \cdot \mathbf{0} \\
& B=!b \cdot \tau_{B} \cdot \bar{c} \cdot \mathbf{0} \\
& C=!c \cdot \tau_{C} \cdot(\bar{a} \cdot \mathbf{0}+\bar{d} \cdot \mathbf{0}) \\
& D=d \cdot \tau_{D} \cdot D^{\prime}
\end{aligned}
$$

## Arbitrary Cycles

## Implicit Termination

- The implicit termination pattern terminates a sub-process if no other activity can be made active
- Problem: Most engines terminate the whole workflow if a final node is reached
- The pi-calculus contains the final symbol $\mathbf{0}$


## Multiple Instance Patterns

- Multiple instance patterns create several instances (copies) of workflow activities



## MI without Synchronization

$$
\begin{aligned}
& A=\tau_{A} \cdot \bar{b} \cdot \bar{b} \cdot \bar{b} \cdot \mathbf{0} \\
& B=!b \cdot \tau_{B} \cdot \bar{c} \cdot \mathbf{0} \\
& C=\text { c.c.c. } \tau_{C} \cdot C^{\prime}
\end{aligned}
$$

$$
A|B| C \equiv \tau_{A} \cdot\{\bar{b}\}_{1}^{n} \cdot \mathbf{0}\left|!b \cdot \tau_{B} \cdot \bar{c} \cdot \mathbf{0}\right|\{c\}_{1}^{n} \cdot \tau_{C} \cdot C^{\prime}
$$

MI with a priori Design Time Knowledge

$$
\begin{aligned}
& \\
A & =\tau_{A} \cdot A_{1}(c) \\
A_{1}(x) & =(\mathbf{v} y) \bar{b}\langle y\rangle \cdot y\langle x\rangle \cdot A_{1}(y)+\bar{x} \cdot \mathbf{0} \\
B & =!b(y) \cdot y(x) \cdot \tau_{B} \cdot y \cdot \bar{x} \cdot \mathbf{0} \\
C & =c \cdot \tau_{C} \cdot C^{\prime}
\end{aligned}
$$

The pattern works like a dynamic linked-list:


## MI without a priori Runtime Knowledge



## MI with a priori Runtime Knowledge

## State-based Patterns

- State-based patterns capture implicit behavior of processes that is not based on the current case rather than the environment or other parts of the process



## Deferred Choice



## Interleaved Parallel Routing

$$
\begin{aligned}
A & =\operatorname{check}(x) \cdot\left([x=\top] \tau_{A 1} \cdot A^{\prime}+[x=\perp] \tau_{A 2} \cdot A^{\prime \prime}\right) \\
B & =M(\perp) \mid b \cdot \bar{m}\langle\top\rangle \cdot \tau_{B} \cdot \bar{m}\langle\perp\rangle \cdot B^{\prime} \\
M(x) & =m(x) \cdot M(x)+\overline{\operatorname{check}}\langle x\rangle \cdot M(x)
\end{aligned}
$$

## Milestone

## Cancelation Patterns

- The cancelation patterns describe the withdrawal of one or more processes that represent workflow activities

$$
A \mid \mathcal{E} \equiv a \cdot \tau_{A} \cdot A^{\prime}+\text { cancel } . \mathbf{0} \mid!\tau_{\mathcal{E}} \cdot \overline{\text { cancel }} . \mathbf{0}
$$

## Cancel Activity

## Cancel Case

- The cancel case pattern cancels a whole workflow instance
- This is equal to Cancel Activity with the exception that all remaining processes receive a global cancel trigger


# Data Representation 

$$
\begin{gathered}
C E L L \stackrel{\text { def }}{=} \nu c \overline{c e l l}\langle c\rangle \cdot\left(C E L L_{1}(\perp) \mid C E L L\right) \\
C E L L_{1}(n) \stackrel{\text { def }}{=} \bar{c}\langle n\rangle \cdot C E L L_{1}(n)+c(x) \cdot C_{2}(x)
\end{gathered}
$$

## Memory Cell



## Pairs,Tuples

$$
\begin{aligned}
& S T A C K \stackrel{\text { def }}{=} \nu s \nu e m p t y \overline{\text { stack }}\langle s, \text { empty }\rangle .\left(S T A C K_{0} \mid S T A C K\right) \\
& S T A C K_{0} \stackrel{\text { def }}{=} \overline{\text { empty }} \cdot S T A C K_{0}+s(\text { newvalue }) \cdot \text { triple }(\text { next }) . \\
& \overline{n e x t}\langle\perp, \perp, \text { newvalue }\rangle . S T A C K_{1}(\text { next }), \\
& S T A C K_{1}(\text { curr }) \stackrel{\text { def }}{=} \operatorname{curr}(\text { prev, test, value }) \cdot(\bar{s}\langle\text { value }\rangle . \\
&\left([\text { test }=\top] S T A C K_{1}(\text { prev })+[\text { test }=\perp] S T A C K_{0}\right)+ \\
& s(\text { newvalue }) \cdot \operatorname{triple}(\text { next }) \cdot \overline{n e x t}\langle\text { curr }, \top, \text { newvalue }\rangle . \\
&\left.S T A C K_{1}(\text { next })\right) .
\end{aligned}
$$

## Stack

$$
\begin{aligned}
& \text { QUEUE } \stackrel{\text { def }}{=} \nu q \nu \text { empty } \overline{q u e u e}\langle q, \text { empty }\rangle .\left(Q U E U E_{0} \mid\right. \text { QUEUE) } \\
& Q U E U E_{0} \stackrel{\text { def }}{=} \overline{\text { empty }} . Q U E U E_{0}+q(\text { newvalue }) . \text { triple (newtriple). } \\
& \overline{\text { newtriple }}\langle\perp, \perp \text {, newvalue }\rangle \text {. QUEUE } 1_{1} \text { (newtriple, newtriple) } \\
& \text { QUEUE }_{1}(\text { first, last }) \stackrel{\text { def }}{=} \text { first (next, test, value). }(\bar{q}\langle\text { value }\rangle . \\
& \left([\text { test }=\mathrm{T}] \text { QUEUE } E_{1}(\text { next }, \text { last })+[\text { test }=\perp] \text { QUEUE } 0\right)+ \\
& q \text { (newvalue).triple(newtriple). } \overline{\text { newtriple }}\langle\perp, \perp, \text { newvalue }\rangle \text {. } \\
& \text { last (oldnext, oldtest, oldvalue). } \overline{\text { last }}\langle\text { newtriple, } \top \text {, oldvalue }\rangle \text {. } \\
& \text { QUEUE } 1 \text { (first, newtriple). }
\end{aligned}
$$

## Queue

$$
I \stackrel{\text { def }}{=} s(x) \cdot \tau_{I} \cdot I+e m p t y \cdot I^{\prime}
$$

## Descructive Iterator

$$
\nu \top \nu \perp S
$$

$T R U E=\overline{\text { true }}\langle T\rangle$. TRUE $\quad F A L S E=\overline{\text { false }}\langle\perp\rangle . F A L S E$

## Booleans

```
    \(A N D \stackrel{\text { def }}{=} \operatorname{cell}(v) \cdot a n d(b 1, b 2, \operatorname{resp}) \cdot b 1(x) \cdot b 2(y) \cdot\left([x=\top][y=\top] \bar{v}\langle T\rangle \cdot A N D_{1}+\right.\)
    \(\left.[x=\perp] \bar{v}\langle\perp\rangle . A N D_{1}+[y=\perp] \bar{v}\langle\perp\rangle . A N D_{1}\right)\)
\(A N D_{1} \stackrel{\text { def }}{=}(\overline{r e s p}\langle v\rangle . \mathbf{0} \mid A N D)\).
```


## Conjunction

$\square$
OR $\stackrel{\text { def }}{=} \operatorname{cell}(v) . o r(b 1, b 2, r e s p) . b 1(x) . b 2(y) .\left([x=\perp][y=\perp] \bar{v}\langle\perp\rangle . O R_{1}+\right.$ $\left.[x=\mathrm{T}] \bar{v}\langle\top\rangle . O R_{1}+[y=\top] \bar{v}\langle\top\rangle . O R_{1}\right)$
$O R_{1} \stackrel{\text { def }}{=}(\overline{r e s p}\langle v\rangle . \mathbf{0} \mid O R)$.

## Disjunction

$$
\begin{aligned}
N E G \stackrel{\text { def }}{=} & n e g(b, \text { resp }) \cdot \operatorname{true}(t) \cdot f \text { false }(f) \cdot b(x) \cdot( \\
& ([b=t] \overline{\text { resp }}\langle\text { false }\rangle \cdot \mathbf{0}+[b=f] \overline{\text { resp }}\langle\text { true }\rangle . \mathbf{0}) \mid N E G)
\end{aligned}
$$

## Negation

$$
\begin{gathered}
\langle\perp, \perp, \top, \perp, \top, \perp, \top, \perp\rangle \\
B Y T E_{42} \stackrel{\text { def }}{=} \frac{\text { byte }_{4} 2}{}\langle\perp, \perp, \top, \perp, \top, \perp, \top, \perp\rangle . B Y T E_{42}
\end{gathered}
$$

## Bytes

## Further structures

- More structures are possible:
- Natural numbers based on extended queues
- Lists using natural numbers as indices (why?)
- Strings
- etc.


# Workflow Data <br> Patterns 



## Data Layers



## Activities and Data

## Some Sample Data Patterns

- Activity data
- Complex activity data
- Scope data
- BPMS data
- Data interaction:Activity to Activity
- Data interaction: Complex activities


## Activity Data

- Data elements can be defined by activities which are accessible only within the context of individual execution instances of that activity:

$$
A \stackrel{\text { def }}{=} \nu x \operatorname{cell}(c) \cdot \tau \cdot \mathbf{0}
$$

## Complex Activity Data

- Complex activities are able to define data elements, which are accessible by each of their components:

$$
C \stackrel{\text { def }}{=} q u e u e(q, e) \cdot(A \mid B)
$$

## Scope Data

- Data elements can be defined which are accessible by a subset of the activities in a process instance:

$$
I \stackrel{\text { def }}{=}(A|B| \nu z(C \mid D))
$$

## BPMS Data

- Data elements are supported which are accessible to all components in each and every process instance and are within the control of the business process management system (BPMS):

$$
B P M S \stackrel{\text { def }}{=} \operatorname{stack}(s, e) \cdot\left(P_{\text {enact }}\right) \text { and } P_{\text {enact }} \stackrel{\text { def }}{=} \operatorname{start} .\left(P \mid P_{\text {enact }}\right)
$$

## Data Interaction: Activity to Activity

- The ability to communicate data elements between one activity instance and another within the same process instance:

$$
P \stackrel{\text { def }}{=} \nu d(\operatorname{cell}(a) \cdot \tau \cdot \bar{d}\langle a\rangle \cdot \mathbf{0} \mid d(x) \cdot \tau \cdot \mathbf{0})
$$

## Data Interaction: Complex Activities

- The ability to pass data elements to/from a complex activity:

$$
\begin{gathered}
C \stackrel{\text { def }}{=} d(x) \cdot(A \mid B) \\
C \stackrel{\text { def }}{=} \nu c 1 \nu c \mathcal{Z}(\operatorname{cell}(u) \cdot \tau \cdot \overline{c 1}\langle u\rangle \cdot \mathbf{0}|\nu v \tau \cdot \overline{c \mathcal{c}}\langle v\rangle \cdot \mathbf{0}| c 1(x) \cdot c \mathcal{L}(y) \cdot \bar{d}\langle x, y\rangle . \mathbf{0})
\end{gathered}
$$

